SSI 3025 Digital Panel Meter



for Absolute Encoders with Synchron-Serial-Interface

Instruction Manual





Warrantv

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Technical subjects to change

1. Description

The digital panel meter Model SSI 3025 is an instrument for displaying and controlling absolute encoders with **Synchronous-Serial-Interface (SSI)**

Standard functions

- · Zero point adjustment
- · Offset value
- · Scaling factor
- Master/slave

2. Safety instructions

This instrument is produced in accordance with Class II of IEC 348 and VDE 0411. When delivered the instrument has been tested to meet all functions described. Before installing the instrument please read the mounting and servicing instructions.

We have no liability or responsibility to customer or any other person or entity with respect to any liability, loss or damage caused or alleged to be caused directly or indirectly by equipment or software sold or furnished by us. Read the installation instruction carefully. No liability will be assumed for any damage caused by improper installation.

Inspect the instrument module carton for obvious damage. Be shure there are no shipping and handing damages on the module before processing. Do not apply power to the instrument if it has been damaged.

ERMA's warranty does not apply to defects resulting from action of the buyer, such as mishandling, improper interfacing, operation outside of design limits, improper repair or unauthorized modifications.

2.1. Symbol explanation









Caution Attention Instruction Tip

Caution: Will be used at dangerous for life and health!

Attention: Will cause damage

Instruction: If not noticed, trouble may occur
Tip: Useful hints for better operation

3. Mounting

3.1. Place of operation

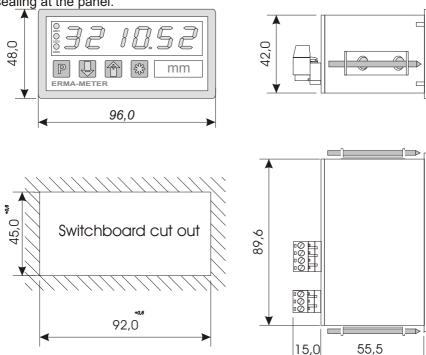
Attention must be payed to the protection against humidity, dust and high temperatures at the place of operation.

3.2. Mounting of digital panel meter

3.2.1. Housing for switch board

Insert the case into the panel cutout (according to DIN 43700: 92^{+0,8} x 45^{+0,6} mm)

• Tighten the screws alternately, using enough pressure to get good retention and sealing at the panel.



4. Electrical connections

4.1. General instructions

- It is forbidden to plug or unplug connectors with voltage applied
- Attach input and output wires to the connectors only without voltages applied



- Cords must be provided with sleeves
- Attention must be paid that the power supply voltage applied will agree with voltage noticed at the name plate.
- The instrument has no power-on switch, so it will be in operation as soon as the power is connected.

4.2. Hints against noisy environment

All inputs and outputs are protected against noisy environment and high voltage spikes. Nevertheless the location should be selected to ensure that no capacitive or inductive interference can have an effect on the instrument or the connection lines.

It is advisable:

- To use shielded cables.
- The wiring of shields and ground (0V) should be star-shaped.



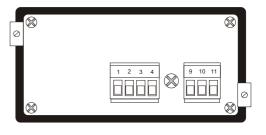
- The distance to interference sources should be as long as possible. If necessary, protective screen or metal enclosures must be provided.
- Coils of relays must be supplied with filters.
- Parallel wiring of input signals and AC power lines should be avoided.

4.3. Connection and pin assignment

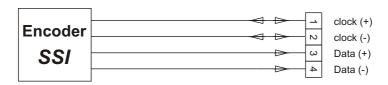
All inputs and outputs are connectors, designed as plug-in screw terminals.

Pin assignment:

Pin Discription							
1	SSI clock input +						
2	SSI clock input -						
3	SSI data input +						
4	SSI data input -						
9	GND						
10	Power supply -						
11	Power supply +						



4.4. Connection of absolute encoder



4.5. Connection of power supply voltage



5. Startup Procedure



Attention must be paid that the power supply voltage applied will agree with the voltage noticed at the name plate. Switch the power supply on (supply voltage applied to 10 (-) and 11 (+)).

When delivered, the instrument is programmed with a standard configuration (default values). By programming the customer can change the standard configuration according to his measuring task.

When the instrument is built in a machine and the customer wants to change the configuration, attention must be paid, that no damage will occur to the machine!

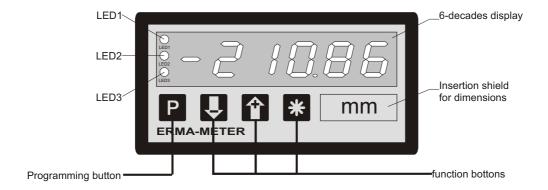
6. Pushbuttons- and LED-functions

There are four push buttons in the front. These push buttons can have different functions. The functions of the push buttons can be used for programming and for service.

6.1. Function of buttons and LEDs

LED 3	Description
off	encoder- or hold value is displayed
green/flashs	programming mode is activated

LED 1 and LED 2 are not used and have no function



7. Modes

The operation and the programming of the panel meter is organized in several states:

- · Operation level
- · Access-code level
- · Programm level

7.1. Operation level

In the state "operation level" the normal functions of the instrument are activated. A normal measurement cycle looks like below:

· Read the value of encoder, calculate and display

The function of the ** -key depends on the value of the parameter **0-08** .

Parameter 0-08 Function of pushbutton "*"	* by pressing
0	No function
1	displayed encoder value is set to zero
2	clear zero setting

7.2. Access-code level

The state "access-code level" becomes active by pressing the pushbutton ring the state "operation level". The display shows "c000". During the state "access-code level" the normal functions of the instrument are active.

pushbutton	Function					
P Confirm of the displayed access-code						
Increase the access-code						
Decrease the access-code						
* no function						

7.3. Programming level

The state "programm level" becomes active by entering the right access-code. The access-code must be confirm by pressing the pushbutton \blacksquare . The programming is organized in following steps:

- Selection of a programming level
- · Selection of a parameter
- · Change of the selected parameter

Pushbutton	Press	Pressing during 3 sec.
P	Selection of - Programming level - Parameter	-
Û	Decrease of - Programming level - Number of parameter - Value of parameter	-
Ŷ	Increase of - Programming level - Number of parameter - Value of parameter	-
*	-	Break the programming routine

8. Procedure of programming

The procedure of programming is organized in several different steps.

Access to the selection of the programming levels

- Pressing pushbutton
 => access-code enter is active
- The display shows "c000"
- Changing the access-code by pressing the pushbutton or and confirm the changed access-code by pressing the pushbutton

If the entered access-code is not correct, the instrument will jump back to the state "operation level".

8.1. Changing or controlling parameters

Activating the programming routine

- Pressing pushbutton
- · LED 3 flashs green
- The display shows "c000"
- Changing the access-code by pressing the pushbutton
- Confirm access-code by pressing the pushbutton
- The display shows "P-00"

Leaving the programming routine

- Pressing the pushbutton until the display shows "PEnd"
- Confirm the display "PEnd" by pressing the pushbutton
- · LED 3 is off
- The active state of the panel meter is "operation level"

Selection of the programming level

- Selecting the programming level by pressing the pushbutton
- Confirm the programming level by pressing the pushbutton
- The display shows the number of the parameter of the selected programming level For example: "0-00" => parameter 0 of the programming level 0

Leaving the programming level

- Pressing the pushbutton or until the display shows "xEnd"
 For example: "0End" => leaving programming level 0
 For example: "2End" => leaving programming level 2
- Confirm the display "xEnd" by pressing the pushbutton
- The display shows the programming level
 For example: "P-00" => for programming level 0

Selection of the parameter

- Selection the parameter by pressing the pushbutton or or
- Confirm the parameter by pressing the pushbutton
- The display shows the last programmed value of the selected parameter

Change and controll the selected parameter

- Change the value of the parameter by pressing the pushbutton 🖳 or 🛍
- Confirm the value of the parameter by pressing the pushbutton
- The display shows the programming level and the number of the parameter For example: "0-05" => parameter 5 of programming level 0

8.2. Overview of the programming levels

The parameters of the panel meter series are organized in different programming levels. According to the design of the panel meter there are several programming levels available.

P-00: Programming level for configuration of the panel meter

The configuration is used to adapt the absolute encoder and the panel meter.

8.3. Programming level for configuration P-00

Param.	Description	Setting range	Default value
0-00	Resolution (Bits)	9 32	12
0-01	Output code 0 -> Gray 1 -> Binary	0 1	0
0-02	Master/Slave-Mode 0 -> Instrument = Master 1 -> Instrument = Slave	0 1	0
0-03	Zero adjustment 0 -> Zero adjustment without sign 1 -> Zero adjustment with ± display	0 1	0
0-04	Counting direction 0 -> increasing clockwise rotation 1 -> increasing anticlockwise rotation	0 1	0
0-05	Scalingfactor	0.00001 9.99999	1.00000
0-06	Offset value	-99999 999999	0
0-07	Programmable decimal points 0 -> XXXXXX 1 -> XXXXX.X 2 -> XXXX.XX 3 -> XXX.XXX 4 -> XX.XXXX 5 -> X.XXXXX	05	0
0-08	Function of pushbutton "*" 0 -> No function 1 -> Taring of encoder 2 -> Clear tara value of encoder	0 2	0
0-09	Clock for Master-Mode 0 -> Frequency = 200 kHz 1 -> Frequency = 100 kHz 2 -> Frequency = 500 kHz 3 -> Frequency = 1 MHz	03	1
0-10	Number of removed most significant bits from the encoder data	0 31	0
0-11	Number of removed least significant bits from the encoder data	0 31	0
0-12	Access-code	0 999	0
0End	Leaving programming level 0		

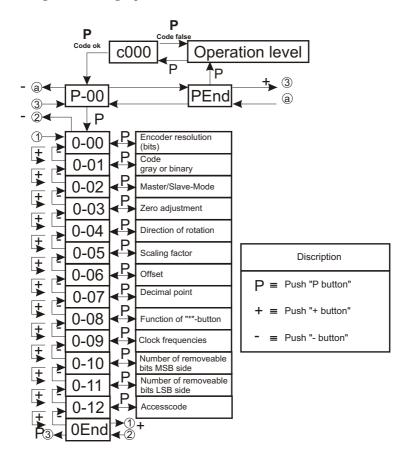
8.4. Scaling the display range

The scaling of the display range is matched by using a scaling-factor and an offset value. The calculation of the display value looks like below:

The overflow or underflow becomes active, if the displayed value is greater than 999999 or smaller than -99999.

- When overflow is activ the display shows "nnnnnn"
- · When underflow is active the display shows "uuuuuu"

8.5. Programming quick reference



9. Software functions

9.1. Master/Slave-Mode

Master-Mode Parameter 0-02 have to be programmed to 0

For reading the value of the encoder the clock is generated by the instrument. A fixed clock frequency of 100kHz, 200 kHz, 500kHz or 1Mhz is generated by the instrument.

Slave-Mode: Parameter 0-02 have to be programmed to 1

The clock signal have to be generated by an other instrument. The data transmission between the encoder and the instrument dependent on this "external clock".

In slave mode attention should be paid to:

- External clock may not exceed 500 kHz
- Pause of clock brushs have to be min. 500 μs
- The encoder value can be displayed with 80 values per second

9.2. Zero point adjustment

Sometimes an exactly mechanical zero point adjustment isn't possible. But it's possible to adjust the zero point by software.

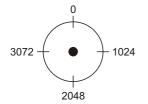
9.2.1. Zero point adjustment by pressing button

The zero point can be changed by pressing the button. Parameter 0-08 have to be programmed to 1.

1. Zero point adjustment with sign: Parameter 0-03 have to be programmed to 1

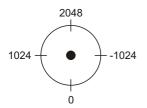
Example:

Absolute Encoder SSI-Encoder, singeltur'n Resolution: 4096 steps per rotation



Display range without changing of the zero point

Display range with changing of the zero point



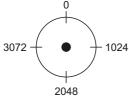
The pushbutton * have been pressed by a display of 2048

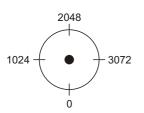
2. Zero point adjustment without sign: Parameter 0-03 have to be programmed to 0

Example:

Absolute Encoder SSI-Encoder, singleturn Resolution: 4096 steps per rotation

Display range without changing of the zero point





Display range with changing of the zero point

The pushbutton * have been pressed by a display of 2048

9.2.2. Zero point adjustment by offset value

The calculation of the programmed offset value (parameter 0-06) looks like below:

Display = (Enc yalue - Zero adjustmet) x Sca faktor + Offset value

There can be a ± display, as a result of programming an offset value.

Attention should be paid to:



- The charging of the offset value is followed **after** the charging of the scaling-factor.
- The Parameter 0-03 have to be programmed to 1 for a ± display

9.3. Directions of rotations

The direction of rotation can be changed by software function. The encoder will usually count in increasing direction, if the driving shaft turns with clockwise rotation (top view at the driving shaft).

Increasing values with clockwise rotation (top view at the driving shaft), Parameter 0-04 have to be programmed to 0

Increasing values with anti-clockwise rotation (top view at the driving shaft), Parameter 0-04 have to be programmed to 1

9.4. Removing bits of the encoder value

The parameters 0-10 and 0-11 can be used to set the number of bits which will be ignored processing the encoder data. In parameter 0-10 the number of the leading bits which will be ignored is set; in parameter 0-11 the number of the lower bits to be ignored is set. For example the parameter 0-10 is set to 3. This means the 3 leading bits of the encoder data are ignored forming the position value.

Example1:

Parameter 0-00 is set to 13. This means 13 data bits are read out of the encoder. Therefore the encoder has a maximum resolution of 13 bits = 8192 steps.

Parameter 0-10 is set to 3. The 3 leading bits of the encoder data are ignored forming the value. Therefore the encoder now has a maximum resolution of 10 bits = 1024 steps.

Example 2:

Processing the data sent from an encoder the SSI 3025 normally expects that the first bit which is sent is the MSB of the position data. Now some types of encoders are sending other informations (e.g.: a present bit) or zeros before the MSB of the position data is sent.

E.g.: it is possible that you have an encoder which is said to be an14 bit encoder but the resolution is only 12 bit and the first two MSBs are zeros; that would lead to an incorrect mearured value. The parameter P0-10 can be used if leading zeros in the encoder data should not be taken into consideration. If you have an encoder which is sending zeros before the position data you have to do the programming as follows:

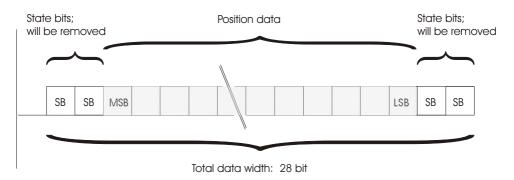
- -set the parameter in P0-00 to the complete number of bit (zeros included)
- -set the parameter in P0-11 to the number of zeros which are used as leading bits before the actual position value starts.

Example 3:

You've got an encoder which is sending status bits before the position data as well as after the position data. The position data have a width of 24 bits and before the MSB 2 status bits are sent and after the LSB two more status bits are sent. The SSI 3025 shall work in the slave mode. The data from the encoder shall also be sent to a computer which processes both the status bits as well as the position data. The SSI 3025 shall only process the position data. Therefore the following settings have to be made:

- Parameter 0-00 has to be set to 28 which is the sum of the 24 bits of the position data and the 2 x 2 status bits.
- Parameter 0-10 has to be set to 2 to remove the 2 status bits before the MSB of the position data.
- Parameter 0-11 has als to be set to 2 to remove the 2 status bits after the LSB of the position data.

With these settings the display will show the correct position data of the encoder even when status bits are transfered together with the position data.



9.5. Main reset

The main reset is performed by pressing a key combination at the front of the panel meter. By doing this all parameters are setting to the default value. The value of the parameter 0-00 (input range) is not changing by the main reset. During the main reset the display shows "Init.".

Perform the main reset by

Pressing the pushbuttons * , • and P at the same time until "InIt" is displayed.

10. Error codes

10.1. Encoder not connected "Err01"

- · The display flashs and indicate "Err01"
- Signalizes that no encoder have been connected to the instrument

10.2. Waiting for data input "Err02"

- The display flashs and indicate "Err02"
- Signalizes in slave-mode, that after the connection of an encoder no data input have been received by the instrument.

10.3. External clock frequency too high "Err03"

- The display flashs and indicate "Err03"
- Signalizes in slave mode, that the clock frequency of the "external clock" is too high (> 500 kHz).

11. Technical Specifications

11.1. Electrical datas

SSI signal input : singleturn or multiturn

Resolution : 9 .. 32 bit Code : binary or gray : driver RS 422/485 Clock output Clock input : receiver RS 422/485 : receiver RS 422/485 Data input

Master mode

Clock frequency : internal 100kHz,200 kHz,

500kHz or 1MHz

Conversion rate : approximate 80 values/second

Slave mode

Clock frequency : external, max. 500 kHz

Break of clock brushs : min. 500 us

Conversion rate : approximate 80 values/second

: 18 .. 36 V DC (isolated) Power supply DC

power consumption : max. 50 mA

: 12 V DC, ± 10 % (isolated) optional

power consumption : max. 100 mA

: 5 V DC, ± 10 % (isolated) optional

power consumption : max. 200 mA Isolation voltage : 500 V /1 min

11.2. Mechanical datas

Display : 6 decades, 14 mm, red

> : decimal point programmable : preliminary zero suppression

: - sign at negative values

Operation, keyboard design : front membrane with push buttons

: panel mounting DIN 43 700 Case

: 96 x 48 x 63.5 mm

Dimensions (B x H x T) Depth : 72 mm incl. screw terminal Mounting

: switch board mounting or : mosaic-system mounting

Weight : approx. 160 g

: plug-in screw terminal Connection

11.3. Environmental conditions

Operating temperature : 0 .. 50 °C Storage temperature : -20 .. 70 °C

Humidity : < 80 %, not-condensing Protection : protection class II

Front protection : IP 54

: connectors IP 20

Field of application : class 2

: overvoltage protection II : in conform with 89/336/EWG

: NSR 73/23/EWG

12. Ordering Information

CE

SSI 3025 -		0		0					
					Housing				
					switch board mounting				
					1 panel-clip mounting				
				rese	rved				
			Fron	t desi	gn				
			0	reserved					
			1	ERMA-Meter Logo no Logo customer defined Logo					
			2						
			3						
		resei	rved						
	Pow	er sup	ply	10 % (isolated)					
	0	5 V D	OC, 10						
	1	12 V	DC, 10	10 % (isolated) DC (isolated)					
	2	18	36 V I						

13. Notes

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